

Computational Cost of Direct Numerical Simulations

To perform a direct numerical simulation (DNS) of some fluid flow, the number of grid points must accurately capture all scales of motion. This means that the number of grid points N in one direction must span the largest scale of the motion at the integral length scale L , but must also capture the smallest scales of motion at the Kolmogorov length scale η . This means at minimum,

$$N \approx \frac{L}{\eta}. \quad (1)$$

The Kolmogorov length scale (in m) is defined as

$$\eta = \left(\frac{\nu^3}{\varepsilon} \right)^{1/4}, \quad (2)$$

where ν is the viscosity in $\text{m}^2 \text{s}^{-1}$, and ε is the turbulence dissipation rate in $\text{m}^2 \text{s}^{-3}$. This rate ε can be written as

$$\varepsilon = \frac{u^3}{L}, \quad (3)$$

where u is velocity in m s^{-1} . Substituting these definitions into Equation 1, we see that

$$N \approx \frac{L}{\eta} \quad (4)$$

$$\approx L \left(\frac{\varepsilon}{\nu^3} \right)^{1/4} \quad (5)$$

$$\approx \frac{L}{\nu^{3/4}} \left(\frac{u^3}{L} \right)^{1/4} \quad (6)$$

$$\approx \frac{L^{3/4} u^{3/4}}{\nu^{3/4}} \quad (7)$$

$$\approx \text{Re}^{3/4}. \quad (8)$$

We then estimate that the number of floating-point operations in one direction (N) is proportional to the number of grid points (three dimensions) plus the number of time steps (one “dimension”). Thus, the computational cost of a DNS with N^4 grid points scales with Re^3 .